Operating Instructions 4064 SK.



Always on the safe side.





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A 1 User information

A 1.1 Meaning of the pictograms

Situations where failure to follow the instructions may lead to danger, damage to material or operating faults.

Important information for operator



and engineer.

Automatic mode Automatic sequence



Close, screw in, fasten, etc.

Open, release, loosen

+ more, higher

- less, lower
- ∞ Continuous operation

① Time, time sequence

 $\underbrace{\bigcirc}_{=}^{\bullet} Disconnect mains plug }$

A 1.2 Important information

The instructions for use should be read by the user before starting up the unit for the first time, in order to avoid incorrect operation and other damage. If other language versions are required, please request these from your responsible KaVo agent. Duplication and distribution of the instructions for use (IU) require KaVo's prior consent.

All technical data, information and properties of the product described in the IU correspond to the state on going to press.

Modifications and improvements to the product as a result of new technical developments are possible.

This does not imply any right to retrofitting of existing units.

KaVo assumes no responsibility for damage arising through:

- external influences (poor quality of the media or inadequate installation)
- use of incorrect information
- improper use
- improperly performed repairs.

Repair and maintenance work - apart from the activities described in these instructions for use - may be performed only by qualified technical personnel.

In the event of modifications by third parties, the approvals become null and void. KaVo recommends using only original spare parts for operation and for repair.

A 1.3 Precautions

Safe operation and protection of the unit are ensured only through proper use in accordance with the instructions for use and using the tools approved for the purpose. The following should also be observed:

- the tool manufacturer's instructions,
- the work safety regulations,
- the accident prevention regulations.



■ Each time before switching on, check the set speed.

■ Observe the permissible maximum speed and maximum pressure of the tools (according to tool manufacturer's instructions).

■ Use safety screens when working with rotating tools.

■ To avoid danger through accidental switching on, place the handpiece on a suitable shelf or tool support.

In the event of an unsatisfactory condition of the unit or improper use, e.g.:

- unsuitable tools
- tool shafts not manufactured according to DIN-ISO
- improper use or use not in accordance with the purpose
- unapproved speeds for tools used
- incorrect clamping of the tools in the chuck
- insufficient retaining force of the chuck (wear, soiling, failure to follow the product care instructions for the chuck system, etc.)
- different sizes of tool shaft and chuck
- lack of regular cleaning of the chuck
 failure to follow the maintenance instructions
- failure to comply with the accident prevention regulations (e.g. failure to use safety screens, safety devices, etc.)

• Non-conformity with the EMW Guidelines regarding radiation from low frequency, radio frequency and microwaves (use shielded cable)

- failure to take into account signs of wear and damage
- tool shafts which have slipped out (potential danger = bending of the tool shafts)
- operating the spindle when not connect ed to compressed air can cause defects

there is a danger of injury and damage to material and unit, e.g. due to:

- Bending of the tool shafts
- Accidental withdrawal of the tools from the chuck
- Breaking or splintering of the tool.
- Eccentric rotation or shattering of tools, or
- Snagging and rolling up

• Catapulting of small material-parts in order to prevent this, safety precautions must be incorporated into the unit.

Any liability shall be excluded if defects or the consequences thereof are due to manipulation or modification to the product by the customer or by any third parties not authorized by KaVo.

The electro-magnetic compatibility analysis must be carried out and evaluated in conjunction with the commutator.

A 1.4 Possible uses and applications

The motorised spindle 4064 SK is designed to be used in machines for filing processes, such as drilling, milling, cutting etc.

A 2 Scope of delivery - Accessories

A 2.1 Scope of delivery

Check to make sure delivery is complete:

1 HF Motor-spindle 4064 SK with dummy





Fork spannerl 7	Mat. No. 1.003.0098
Fork spanner 15	Mat. No. 1.003.0099
Fork spanner 20	Mat. No. 1.003.0100

Set of brushes	Mat. No. 0.411.0190
Consisting of:	
1 Cleaning brush	Mat. No. 0.229.3205
② Fine-hair brush	Mat. No. 0.229.3001
(3) Cylindrical brush	Mat. No. 0.229.3002

Case (Mat. No. 0.684.4116) and padding (Mat. No. 0.684.4109) please retain for use when returning products for inspection or repair.

Operating Instruction Mat. No. 1.002.7869

A 2.2 Optional accessories

For external air or water cooling: Chucking device 4864 Mat. No. 1.002.7351

use shielded cable connecting cable 5 m Mat. No. 1.000.1564

Chuck holder, for sizes up to 6,0 mm Mat. No. 1.002.5075

Chuck holder, for sizes 6,35 and 8,0 mm Mat. No. 1.002.7696









A 3 Electrical connection

Check that the available voltage and frequency agree with the data on the frequency converter.

Repair and maintenance work - apart from the activities described in these instructions for use - may be performed only by qualified technical personnel.

- Dangers from disturbances in the energy supply, breaking of machine parts or other malfunctions, e.g.
- unforseen ejection
- unexpected starting
- unexpected slipping/over-revving
- incorrect rotation (chuck mechanism can loosen)

must be prevented by appropriate safety features incorporated in the control unit (e.g. max. revolutions). KaVo EWL recommends operation by use of Frequency Converter "e@sy Drive 4452 ".



Disconnect the converter plug.

A 3.1 Specifics of the motor connection cable

- 1 PTC cold conductor BR1
- 2 PTC cold conductor BR2
- (3) Potential earthing conductor, green/yellow
- (4) Phase U
- (5) Phase V
- (6) Phase W

Fasten the connecting wires to the converter connection terminal.



Ensure that the ground wire is correctly fixed to the provided grounding terminal.

Pay attention to the rotation of the i spindle (if necessary, exchange two phases)!





A 4 Fitting and commencing operation of HF Motor-spindle 4064 SK



- Air-lock supply of 0,5 to 0,8 bar must be clean and dry.
- Never operate the spindle without air lock.
- The inflow and outflow for air lock must always be kept clear
- Prevent any foreign bodies or lubricants being drawn into the air-lock

Attach the 3 mm air-lock hose 2 to the air-lock connector (1) in the direction of the arrow, then secure.

Installation in spindle holder or clamping device

It is recommended to use Clamping Device 4864 (1.002.7371). Initial torque when clamping the spindle 1,5 Nm \pm 20 % is to be maintained.

Operation in any position between horizontal and vertical (tool pointing down) is possible, using cooling through the spindle holder or an external cooling jacket.



When inserting the spindle ensure it is located cylindrically.

The spindle is designed for cooling via the spindle holder .

Motor spindle 4064 SK is moisture-proof, but must not be immersed in water.

Tension can be applied over the whole housing. However it is recommended to clamp over a wide surface, and when possible in the middle of the spindle.

When commencing operation of HF Motor spindle 4064 SK fit the compressed air hose (3) $d_i = 4 \text{ mm}$, $D_a = 6 \text{ mm}$ in the direction of the arrow to the connection nozzle (4) and connect up.



Use only compressed air (5 - 6 bar). free from dirt, water, and oil.





⚠

- Please apply no violence at all.
- The whole region of the cylinder (Z), as well as the compressed air and the electric connection must be protected against the penetration of dirt and water.
- Spindles must only be mounted and operated in appropriate receptacles and machines, according to the application possibilities of the spindle.
- *Mind the direction of rotation (see arrow on the rating plate).*
- Only operate HF motor spindle 4064 SK with a tool or test-pin clamped in the chuck Avoid, at all times, impact or blows against the spindle or a clamped-in tool.
- Regulations for the prevention of accidents are to be observed!
- Only work with concentric tools.
- Operate the spindle only in a suitableposition.
- A too-high tension is to be avoided (effects the rotation and lifetime of the spindle)



A 5 Changing tools

Removing the tool

To release the chuck holder ②, allow compressed air at a pressure of minimum 5 bar to maximum 6 bar to flow through the air tubing ①.

When the chuck holder ② is loose, pull it out by hand in the direction of the arrow.

Release the tool by loosening the locking nut (5) with open wrench (4), applying reverse pressure with open wrench (3).

Inserting the tool

Tighten the tool corresponding to the shaft length and details from the tool manufacturer.

Tighten the locking nut (5) with open wrench (4), applying reverse pressure with open wrench (3).

To tighten the chuck holder (2) in the spindle, allow compressed air at a pressure of minimum 5 bar to maximum 6 bar to flow through the air tubing (1).

Release the air pressure – chuck holder (2) is now tightened.



A 6 Changing chucks

Changing tools or the chuck holder must be done only when the motorised spindle 4064 SK is at a complete standstill. Ensure that the converter is protected against unexpected operation, e.g.,by pressing the main switch to the "OFF" position.

A 6.1 Removing the chuck

To release the chuck holder ②, allow compressed air at a pressure of minimum 5 bar to maximum 6 bar to flow through the air tubing ①.

When the chuck holder ② is loose, pull it out by hand in the direction of the arrow.

A 6.2 Removing the chuck from the chuck holder

Release the tool by opening the locking nut (5) with open wrench (4), applying reverse presure with open wrench (3).

Remove the tool (9).

Unscrew locking nut (8).

Remove the chuck (7).



2



A 6.3 Inserting the chuck in the chuck holder

Inserting chuck (2), up to size 6,35 mm

Non-observance of the operating instructions when inserting the chuck can cause damage to the chuck and the segment of the locking nut.

Guide the chuck ② at an angle into the locking nut ①.

The segment ④ must engage in the groove ③ of the chuck.

Screw the locking nut (9) (with installed chuck (8)) onto the holder (7).

Insert the required tool (10) into the chuck (8).

Inserting chuck, sizes 6,35 and 8 mm

Guide the chuck (5) straight into the locking nut (6), and use pressure to engage in the cleft.

Screw the locking nut (9) (with installed chuck (8)) onto the holder (7).

Insert the required tool (10) into the chuck (8).

Tightening the tool

Tighten the tool in accordance with the shaft length and details from the tool manufacturer.

Closing the locking nut (1) with open wrench (3), applying reverse pressure with open wrench (2).

A 6.4 Inserting the chuck holder

Insert chuck holder (5) in the direction of the arrow.

To close the chuck holder (5), release the air pressure, chuck holder (5) is tightened.



A 7 Maintenance

- On no account clean the HF Motor-Spindle 4064 SK with ultrasound, steam jet, compressed air, etc.
- Under no circumstances should detergents like e.g. spray purifier, fat solvents, etc. get into the inside of the HF Motor-Spindle 4064 SK.

Clean the chuck (3) regularly.

Changing chuck see A 6.

Clean chuck receptacle (1) and chuck (3) with a brush.

Reinsert the clean chuck 3 with tool ② or test pin ③ in HF Motor-Spindle 4064 SK (see A 6.3-6.4).



A 8 Technical data



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Further installation dimensions, with tolerances, are available on request from KaVo.

> Applicable Standard EN 60034-1 "Rotating electrical machinery"

A 8.1 HF-Spindle 4064 SK

BLDC
230 volts
60 Ncm
3000 watts
50.000 min ⁻¹
12 amps
833 Hz
833 Hz I
833 Hz I IP 54
833 Hz I IP 54 s 3500 grams
833 Hz I IP 54 s 3500 grams g from the left
833 Hz I IP 54 s 3500 grams g from the left 0.5 - 0.8 bar

Analysis of concentricity and stability

Concentricity at the cone: <= 0.003 mm

Concentricity at a distance of 16 mm from the chuck				
at standard- chucks at high prezision- chu	>= 0,015 mm			
at high problem and	>= 0,008 mm			
Load direction	axial + radial			
Operating position	horizontal + vertical pointing down)			
tool changing	pneumatic (5-6 bar)			
Cooling water c	ooling, sh.diagramm			

Ballbearings:

triple system with lifetime lubrication





A 9 Available chucking systems

Standard precision chucks:

Chuck, diameter 2,5 mm Mat. No. 1.002.7689 Chuck, diameter 3,0 mm Mat. No. 1.002.7690 Chuck, diameter 3,175 mm Mat. No. 1.002.7691 Chuck, diameter 6,0 mm Mat. No. 1.002.7693 Chuck, diameter 6,35 mm Mat. No. 1.002.7832







Locking nut, for sizes up to 6,0 mm

Chuck holder, for sizes up to 6,0 mm

Chuck holder, for sizes 6,35 mm and

8,0 mm

Locking nut, for sizes 6,35 mm and 8,0 mm



Mat. No. 1.002.5075

Mat. No. 1.002.7696

Mat. No. 1.002.7695





High precision chucks:

Chuck, diameter 2,35 mm
MatNo. 1.003.2015
Chuck, diameter 2,5 mm
MatNo. 1.003.2022
Chuck, diameter 3,0 mm
MatNo. 1.003.2016
Chuck, diameter 3,175 mm
MatNo. 1.003.2017
Chuck, diameter 4,0 mm
MatNo. 1.003.2018
Chuck, diameter 5,0 mm
MatNo. 1.003.2019
Chuck, diameter 6,0 mm
MatNo. 1.003.2020
Chuck, diameter 6,35 mm
MatNo. 1.003.2021

type D: Chuck, diameter 8,0 mm Mat. No. 1.002.7694





Customer setting 4064 SK

Customer:			Date:							
Motor/spindle: HF - Spindle 4064 SK			Official responsible:							
Remark :										
Cott	•	Description	Dioploy				Unit	Footory	Customor	
Prio	 P	Description	Display	۵SM	BI DC F		Onit	setting	setting	
		Special settings						ootting	ootting	
В	42	Max. motor frequency	f mot max	х	х	х	Hz	f mot nom		
0	43	Max. motor voltage	V mot max	х	х	х	V	U mot nom	230 V	
B	44	Current limit	I limit	х	х	х	A~	1.5 * I nom	12 A	
02	46	Rise time	t rise	х	х	х	S	5.0		
02	47	Delay time	t fall	х	х	х	S	5.0	3 sec.	
02	48	Delay time at stop	t stop	х	х	х	S	t_fall		
02	50	Start option (catch)	Motorstart	х	-	-	-	Normal		
02	51	Start time	t_start	-	х	-	S	without ramp	0.5 sec.	
02	52	Start current	I start	-	х	-	A~	0.4		
02	53	Start frequency	f_start	-	х	-	Hz	5		
02	54	Switch-off time WR	t_off	-	х	-	μs	600		
02	55	DC brake time	t_DC_brake	х	-	-	S	2		
02	56	DC brake current	I_DC_brake	х	-	-	A-	1.0		
02	57	Stop current	I_DC_stop	х	х	Х	A-	OFF		
O2	58	Flag emergency stop at								
		mains failure	emerg.stop	Х	х	х	-	off		
В	59	Speed sensor pulse count	emerg.stop	Х	х	Х	-	no sensor		
		U/f Table								
0	60	Startup voltage	V_start	Х	-	-	٧~	3% U_nom		
0	61	Frequency 1	f1	Х	-	-	Hz	f_mot_nom		
0	62	Voltage 1	V1	Х	-	-	٧~	U_mot_nom		
0	63	Frequency 2	f2	Х	-	-	Hz	f_mot_nom		
0	64	Voltage 2	V2	Х	-	-	V~	U_mot_nom		
0	65	Frequency 3	£3	Х	-	-	Hz	f_mot_nom		
0	66	Voltage 3	V3	Х	-	-	V~	U_mot_nom		
_		Control								
0	70	Control (U/f. I*R, slip, N)	Control	Х	-	-	-	U/f table		
02	71	I*R comp. rise factor	I*R-factor	Х	-	-	V/A	off		
02	72	Load comp. rise factor	Loadkomp.	Х	-	-	%	off		
02	73	I*R and load comp. filter time	comp-T-filt	tΧ	-	-	ms	20		
02	75	Slip comp. P-factor	Slipkomp	Х	-	-	Hz/A	off		
02	76	Slip comp filter time	slip-T_filt	t X	-	-	Hz/A	20		
W	77	Current limitation	I-limtr-KP	Х	Х	Х	%	40		
W	/8	Current limitation	I-limtr-Tn	Х	Х	Х	ms	10		
W	/9	Voltage control	V-contr-KP	Х	Х	Х	%	20		
W	80	Voltage control	V_contr-Tn	Х	Х	Х	ms	10		
03	81	Speed control	N-contr-KP	Х	X	Х	%	50		
03	82	Speed control	N-contr-Tn	Х	Х	Х	ms	250		
03	83	Speed control	N-contr-Tv	Х	Х	Х	ms	30		
03	84	Speed control	N-con-T_fi	1 X	X	Х	ms	200		
-	05	Monitoring:							DEC	
<u>B</u>	85	Sensor type	Motor prot	Х	Х	Х	-	011	PIC	
0	86	Resistance	R_protect	X	X	Х	onm	1200		
F	00	Nominal motor data: (acco	braing to ratio	ng pl	ate)				DIDO	
	90	Nominal fragman su	motortype	X	X	X	-	no motor	BLDC	
<u> </u>	91		t_mot_nom	X	<u>x</u>	X	HZ	00	855	
<u> </u>	92	Nominal voltage	V_mot_nom	X	X	<u>x</u>	V	30	200	
<u> </u>	93	ivominal current	1_mot_nom	X	X	X	A	1.0	<u> </u>	
<u> </u>	94	COS. DNI	cos phi	X	X	X	%	85	98	
E	96	Number of poles	no.ot pole	sХ	Х	Х	-	2		

Setting priority: E = Necessary, minimum input, B = required according to mode, O =set for optimization (opt level) W = best left at factory

Warranty conditions

Under valid KaVo delivery and payment conditions, KaVo gives a warranty of satisfactory function and freedom from faults in material and manufacture for the duration of 12 months from the date of sale certified by the vendor.

In the case of justifiable complaints, KaVo shall supply spare parts or carry out repairs free of charge. KaVo accepts no liability for defects and their consequences which have arisen or could have arisen as a result of natural wear, improper handling, cleaning or maintenance, noncompliance with the maintenance, operating and connecting instructions, corrosion, impurities in the air supply or chemical or electrical influences which are unusual or not admissible in accordance with KaVo's instructions. The warranty claims shall become null and void if defects or their consequences can be attributed to interventions in or modifications to the product. Warranty claims can only be validated if they are notified immediately in writing to KaVo.









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